



## Sensors and actuators lecture notes

Arduino senses the environment by receiving inputs from add-on devices such as sensors, and can control the world around it by adjusting lights, motors, and other actuators. In this class you will learn how and when to use the different types of sensors and how to connect them to the Arduino. Since the external world uses continuous or analog signals and the hardware is digital you will learn how these signals are converted back-and-forth and how this must be considered as you program your device. You'll also learn about the use of Arduino-specific shields and the shields software libraries to interface with the real world. Please note that this course does not include discussion forums. View SyllabusSelect a languageArabicEnglishFrenchGermanItalianRussianSpanishVietnameseptPt[MUSIC] [SOUND] IoT devices have to do something, have to have some output, right? And the output goes to actuators and they cause some event in the real world. Now, this event in the real world might be as simple as putting a message on a screen, right. But it could be more sophisticated than that. Basically, actuators are the outputs of the IoT device. So, could be visual, maybe it's a LED, or set of LEDs, lights go off and on. LCD, liquid crystal display, monitor, right? All these things are output devices, and are actuators. Audio, so maybe it's a buzzer or a speaker, so it can make sounds of some kind. Motion, so they can cause motion. So maybe one of the actuators is a motor, that's a common thing, to move something in a physical world. A valve, or a pump to move water or some kind of liquid, to let them pass through a pipe or something like that. Tactile, so, I don't know if you'd call this tactile, but heating and cooling. You can turn on an air conditioner, like in this building, the control system in this building, the control system, if you talk about the HVAC in the room. So, actuators are just devices that do something in the real world. Now, the simplest type of actuation you can have [COUGH] is what I'll call on-off actuation or power actuation. And all you're doing is controlling the power, the only control that you have with this device is power. Now this is very simplistic control. So even complicated actuators can be controlled via power. Minimal control, but you can do something via power. So LEDs, light emitting diodes, you can just turn them off and on. Now you can be more sophisticated about that. You can make them brighter or darker and all that, but you don't have to. You can just say off, on. You can control them in this digital way. A buzzer. You can make it buzz or not buzz. A monitor, you can power it on or off. Now there are all kinds of devices like that. Basically all devices, you can put up messages on there, draw pictures on there, all kinds of sophisticated things. But if you're doing on-off actuation, all you can do is turn it off and on. So you're controlling it but in a minimal way. With an LED. LED off and on is often enough, but you could make it dimmer or brighter. But with on-off actuation, that's not possible. So this is one way to control an actuator, just through power. On-off control may be all that you need. It depends on the application. Maybe all you need it to turn your LED off or on, in which case on-off actuation is just fine. Lights in a classroom, yes, so like in my office when you walk into the room, the light sensor turns the lights on. And it doesn't set the lights at a certain dimness or brightness or something like that, it's that either they're all on or all off. So it's sufficient. Also, air conditioning, like HVAC systems. Typically, like in my office, the air is on or it's off. It doesn't get in between. So that's mostly satisfactory. One thing to worry about or to be aware of when you're actuating something and especially in this power mode, is to think about the current limits of the device, of both devices on both sides, so your micro controller and your actual actuator. Think about the current limits. So for instance, an LED, typical LED might only be able to make sure somehow that that it only is driven with 20 milliamps. So for instance, putting in an appropriate resistor in series with the LED will, using V equals IR, you can put the right size resistor to make sure the current never exceeds a certain threshold. Now you also have to think about current limits on the other side, on the supply side. So the Arduino, regular Arduino pins or Arduino Uno, regular pins besides the power and ground, the power pin, rather. Regular pins can only supply 40 milliamps is clearly not enough. And I says have a problem. So for instance, if you got a motor that request 50 amperes, then 40 milliamps is clearly not enough. 15 amperes because I think about my quad copter, and those motors can take 10 amperes, 15 maybe. They require a lot of power and the Arduino key be able to supply it, so you need some other power supply. So like on a quad-copter, there's a big fat battery on the Arduino key because I think about my quad copter, and those motors can take 10 amperes, 15 maybe. bottom, and that is the power supply. And my Arduino that I use to drive it, to drive the motors. The Arduino doesn't actually directly feed power to the motor. So it controls access to the power in that sense. And we'll talk more in detail about this in future slides. But, [COUGH] so you gotta be aware of these current limits. The Arduino itself can only supply a certain amount of current. So, if you need an alternate power supply. The device that you are actuating, say a LED, might only be able to take a certain amount of current. And you've got to make sure the Arduino or whatever device it is that drives it, can't supply more current than is necessary, than it can take. Thank you. >> [MUSIC] In Module 1, we introduced the concept of the Internet of Things at a high level, defining the term and outlining its implications. In this module we explore some of the details involved in the design and implementation of IoT devices. Unlike traditional computer-based systems, IoT devices are "embedded" within other devices in order to provide enhanced functionality without exposing the user to the complexities of a computer. The users interact with the device in a natural way, similar to their interactions with any other objects in the world. In this way, an embedded system has an interface that conforms to the expectations and needs of the users. Establishing a natural interface requires that the embedded system interface with the physical world. In this module we will discuss the structure of embedded systems and describe these interactions with the physical world. Download Guide for Authors in PDF Sensors & Actuators, B: Chemical sensors and biosensors, chemical actuators and analytical microsystems. The journal aims to promote original works that demonstrate significant progress beyond the current state of the art in these fields along with applicability to solve meaningful analytical problems. Review articles may only be submitted upon invitation from an Editor of the journal aims to publish works that are supported by experimental results and as such purely theoretical works are not accepted. The analytical performance in all analytical parameters needs to be reported and critically compared with the state of the art. 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